

Exercise Session 4

14.05.

- Gurobi vs. Cplex
- Assignment Problem
- Paths & Matchings next week

Gurobi vs. Cplex: → alternative for the programming exercise

Cplex: - available in Unix pool
- private PC/Laptop:
only compilation

Gurobi
- available as student license
- very similar to Cplex
- not avail. in Unix pool
- nicer API

Example:

```
1 package examples;
2
3 import gurobi.*;
4
5 /**
6  * Example of the usage of the Gurobi API with Java.
7  * The code shows how to build an LP for a multi commodity
8  * flow problem with four given paths.
9  *
10 * @author Torsten Gellert
11 */
12
13 public class SolvingLpWithGurobi{
14
15     /** Contant for the cost of artificial arcs for this particular example. */
16     public static final double M = 1000.0;
17     /** Hide constructor, since this class is an simple example. */
18     private SolvingLpWithGurobi() {
19     }
20
21     /**
22     * Creates a path based LP formulation of the multi commodity flow problem
23     * for the instance shown in the exercise session.
24     * Solves and prints all variables and additional available information.
25     *
26     * @param args The argument list . Not used by the method.
27     */
28
```

```

29 public static void main( String[] args ) {
30     try {
31         GRBEnv env = new GRBEnv("lp.log");
32         GRBModel model = new GRBModel(env);
33
34         populateByColumn(model);
35
36         model.optimize();
37
38         int status = model.get(GRB.IntAttr.Status);
39
40         if (status == GRB.Status.INF_OR_UNBD ||
41             status == GRB.Status.INFEASIBLE ||
42             status == GRB.Status.UNBOUNDED ) {
43             System.out.println("The model cannot be solved because it is "
44                 + "infeasible or unbounded");
45             System.exit(1);
46         }
47
48         System.out.println("Solution status = " + status);
49         System.out.println("Solution value = " +
50             model.get(GRB.DoubleAttr.ObjVal));
51
52
53
54         GRBVar[] vars = model.getVars(); get all variables in model
55         for (int j = 0; j < vars.length; ++j) {
56             System.out.println(vars[j].get(GRB.StringAttr.VarName)
57                 + " " +vars[j].get(GRB.DoubleAttr.X)
58                 + "\tReduced cost = "
59                 +vars[j].get(GRB.DoubleAttr.RC));
60         }
61
62         GRBConstr[] cons = model.getConstrs();
63         for (int i = 0; i < cons.length; ++i) {
64             System.out.println(cons[i].get(GRB.StringAttr.ConstrName) +
65                 ":\tSlack = " +
66                 cons[i].get(GRB.DoubleAttr.Slack) +
67                 "\tPi = "
68                 + cons[i].get(GRB.DoubleAttr.Pi));
69         }
70         dual variable pi
71         model.dispose();
72         env.dispose();
73     } catch (GRBException e) {
74         System.out.println("Error code: " + e.getErrorCode() + ". " +
75             e.getMessage());
76     }
77 }
78
79 /**
80  * Builds all variables and constraints(ranges). These are
81  * stored in a arrays and these array have to be placed in the
82  * first position of the given two dimentional arrays.
83  *
84  * @param model The model for handling with LPs.
85  * @throws GRBException if there occurs an error while build the LP model.

```

```

88     static void populateByColumn(GRBModel model) throws GRBException {
89         //           lb, ub,           obj,           type,
           name
90         GRBVar p_1_1 = model.addVar(0.0, Double.MAX_VALUE, M, GRB.CONTINUOUS, "p_1_1");
91         GRBVar p_2_1 = model.addVar(0.0, Double.MAX_VALUE, M, GRB.CONTINUOUS, "p_1_2");
92         GRBVar p_1_2 = model.addVar(0.0, Double.MAX_VALUE, 4, GRB.CONTINUOUS, "p_2_1");
93         GRBVar p_2_2 = model.addVar(0.0, Double.MAX_VALUE, 4, GRB.CONTINUOUS, "p_2_2");
94
95         // Integrate new variables
96         model.update();
97
98         //add some constraints to the model
99         GRBLinExpr expr = new GRBLinExpr();
100        expr.addTerm(1.0, p_1_2);
101        expr.addTerm(1.0, p_2_2);
102        model.addConstr(expr, GRB.LESS_EQUAL, 3.0, "arc_1_3");
103
104        expr = new GRBLinExpr();
105        model.addConstr(expr, GRB.LESS_EQUAL, 1.0, "arc_1_4");
106
107        expr = new GRBLinExpr();
108        expr.addTerm(1.0, p_2_2);
109        model.addConstr(expr, GRB.LESS_EQUAL, 1.0, "arc_2_1");
110
111        expr = new GRBLinExpr();
112        model.addConstr(expr, GRB.LESS_EQUAL, 1.0, "arc_2_4");
113
114        expr = new GRBLinExpr();
115        expr.addTerm(1.0, p_1_2);
116        model.addConstr(expr, GRB.LESS_EQUAL, 1.0, "arc_3_4");
117
118        expr = new GRBLinExpr();
119        expr.addTerm(1.0, p_1_1);
120        expr.addTerm(1.0, p_1_2);
121        model.addConstr(expr, GRB.GREATER_EQUAL, 2, "commodity_1");
122
123        expr = new GRBLinExpr();
124        expr.addTerm(1.0, p_2_1);
125        expr.addTerm(1.0, p_2_2);
126        model.addConstr(expr, GRB.GREATER_EQUAL, 2, "commodity_2");
127    }
128 }

```

$$\left. \begin{matrix} 1 \cdot p_{12} + 1 \cdot p_{22} \leq 3 \\ \downarrow \end{matrix} \right\} \text{//arc } 1 \rightarrow 3$$

```

130 /*
131 Output:
132
133 Optimize a model with 7 rows, 4 columns and 8 nonzeros
134 Presolve removed 7 rows and 4 columns
135 Presolve time: 0.00s
136 Presolve: All rows and columns removed
137 Iteration      Objective          Primal Inf.      Dual Inf.        Time
138           0      2.0080000e+03    0.000000e+00    0.000000e+00    0s
139
140 Solved in 0 iterations and 0.00 seconds
141 Optimal objective  2.008000000e+03
142 Solution status = 2
143 Solution value    = 2008.0
144 p_1_1 1.0          Reduced cost = 0.0
145 p_1_2 1.0          Reduced cost = 0.0
146 p_2_1 1.0          Reduced cost = 0.0
147 p_2_2 1.0          Reduced cost = 0.0
148 arc_1_3:          Slack = 1.0      Pi = 0.0
149 arc_1_4:          Slack = 1.0      Pi = 0.0
150 arc_2_1:          Slack = 0.0      Pi = -996.0
151 arc_2_4:          Slack = 1.0      Pi = 0.0
152 arc_3_4:          Slack = 0.0      Pi = -996.0
153 commodity_1:      Slack = 0.0      Pi = 1000.0
154 commodity_2:      Slack = 0.0      Pi = 1000.0
155
156 */

```

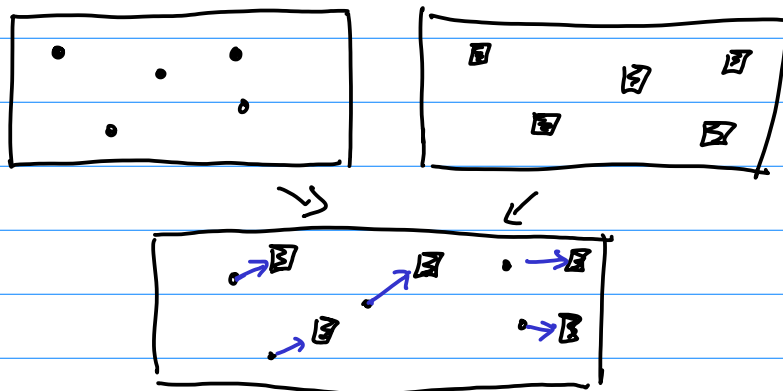
Java ▾ Tab Width

Assignment Problem:

Job Assignment Problem: jobs $j \in J$, each with processing time 1
 m machines, set $X \subset J \times M$, $(j, m) \in X \Leftrightarrow$
 mach. m can process j

Question: is it possible to do all jobs in 1 unit of time

- examples:
- lectures — room (odd. time slots)
 - worker — tasks
 - detecting movements on succ. images



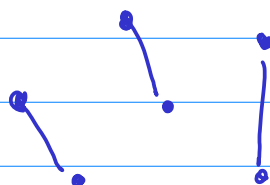
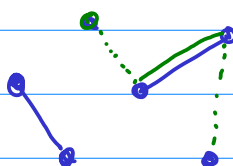
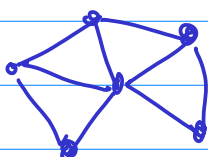
Same problem as Cardinality Matching Problem: in bipartite graphs:

Instance: Undir. Graph $G=(V,E)$, G bipartite

Task: find maximum cardinality set of disjoint edges

Inclusion wise Maximal Matching

Card. Maximal Matching

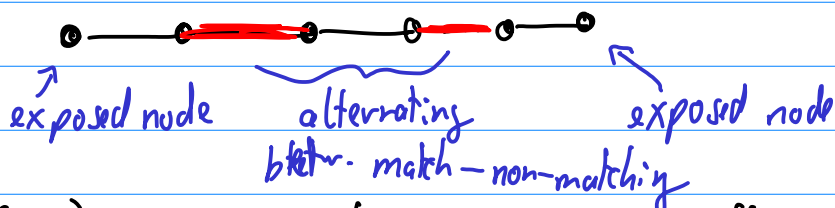


Matching is
- incl. maximal.

- Card. maximal (perfect)
- incl. maximal

finding incl. max Matching: trivial (Greedy)

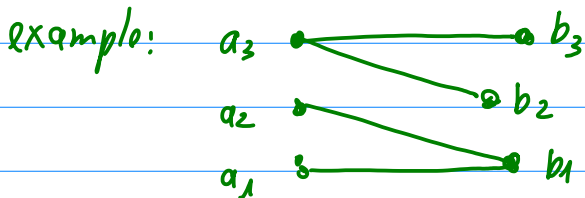
-||- Card. -||- : M-augmenting path



Thm: (Hall): $V = A \cup B$, $G=(V,E)$ has a Matching M $|M|=|A|$ iff
 $|\Gamma(X)| \geq |X| \quad \forall X \subseteq A$

in short: each set X has enough possible matches

$\Gamma(x)$ = neighborhood of x



$$|\Gamma(\{a_1, a_2\})| = |\{b_1, b_2\}|$$

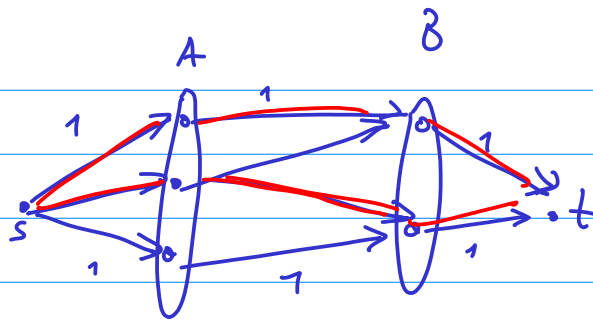
\rightarrow special case $|A|=|B|$

Marriage theorem: version of Hall's thm for $|A|=|B|$, edges are possible candidates for a marriage

Optimality: (Berge) Matching M is maximum iff there is no M-augm. path

Solving: bipartite Matching:

- build s-t flow
- find integral max s-t flow
- path decompos. contains Matching

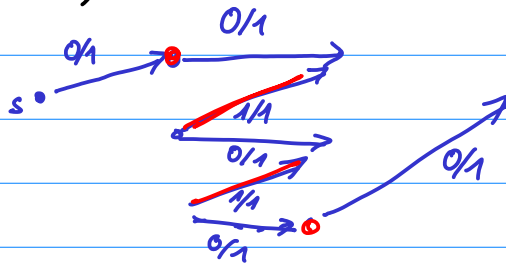


Running time: Edmonds Karp $O(n^3)$

at most $O(n)$ augm. paths

flow augm path:

contains
M-augm. path



Hopcraft-Karp Algo. (1973)

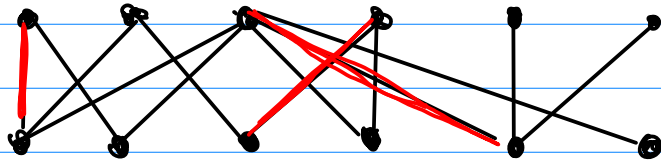
idea: find a lot of augm. paths at once
maximal set of disjoint min. length augm. paths:

- set of M-augm. paths
- vertex set is disjoint
- all path have same length as a min. M-augm. path
- every other augm. path with same length shares a vertex

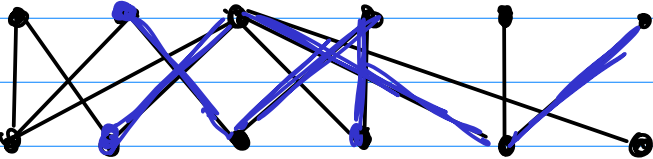
Algo:

- $M = \emptyset$
- find max. set of dis. min. length augm. paths
 $S := \{p_1, \dots, p_k\}$
- while $S \neq \emptyset$
 - $M := M \oplus S$ // augment M with path p_1, \dots, p_k
 - find new set S
- return M

example:

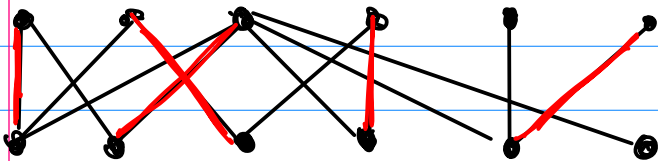


initial Matching, M



set of augm paths, 2 paths S

$M \oplus S$



Running Time:

Lemma 1: (augm. paths are increasing in length)

M is a matching, p is a shortest M -augm path

$M' := M \oplus p$, let q be a M' augm. path

$\Rightarrow |q| \geq |p| + 2|p \cap q|$ (set S maximal \Rightarrow new paths at least longer by 2)

Proof: p, q vertex disjoint $\Rightarrow \checkmark$ p was shortest

$p \cap q = \emptyset$, $M'' := M' \oplus q = M \oplus p \oplus q$

$\rightarrow |M''| = |M| + 2 \Rightarrow M' \oplus M$ contains 2 odd length disjoint

M -augm paths p_1, p_2

$\Rightarrow |p_1|, |p_2| \geq |p| \rightarrow p$ was shortest

$M'' \oplus M = \underbrace{M' \oplus q}_{M''} \oplus M = M \oplus p \oplus q \oplus M = q \oplus p \Rightarrow 2$ M augm paths in $p \oplus q$, not shorter than p

$\Rightarrow |p \oplus q| \geq 2|p|$

$|p \oplus q| = |p| + |q| - 2|p \cap q| \Rightarrow |p| + |q| - 2|p \cap q| \geq 2|p|$

$\Rightarrow |q| \geq |p| + 2|p \cap q| \quad \square$

- we call finding a set S a phase
- after a phase, the length of shortest m -augm. paths grows by at least 2

Lemma: Algorithm runs in $O(\sqrt{n} \cdot m)$ or $O(n^{2.5})$

Proof: • Set S can be found in $O(m)$ → bfs starting at exposed vertices

• number of phases is in $O(\sqrt{n})$ stops if m -augm paths found

• M is matching after \sqrt{n} phases and not maximum

• M^* is maximum, $\Rightarrow |M^*| - |M|$ augm. paths to find

$|M| \oplus |M^*|$ has $|M^*| - |M|$ vertex disjoint augm. paths

• (Lemma 1)

each path has length $\geq 2\sqrt{n} + 1$

• # augm. paths in $M^* \oplus M \leq \frac{n}{2\sqrt{n}+1} \leq \frac{\sqrt{n}}{2}$ (disjoint and length $\geq 2\sqrt{n}$)

• each phase adds at least 1 augm. paths

$\Rightarrow \frac{\sqrt{n}}{2}$ following phases

$\Rightarrow O(\sqrt{n} + \frac{\sqrt{n}}{2}) = O(\sqrt{n})$ phases

each phase in $O(m) \Rightarrow O(m \cdot \sqrt{n}) \quad \square$

→ similar to Dinics Blocking Flow Algorithm