

Open Pit Mining Production Scheduling

- Problem description

- Ultimate pit limits

- Time-indexed IP formulations

Precedence Constrained Knapsack Substructures

- Precedence Constrained Knapsack Problem

- PCKs in open pit mining

- Valid inequalities for the Precedence Constrained Knapsack Polytope

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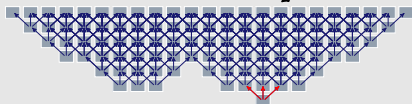
Precedence Constrained Knapsack Problem

PCKs in open pit mining

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Open Pit Mining Production Scheduling

Input



- ▷ block model with precedences
- ▷ deterministic block content
- ▷ ore prices and production costs
- ▷ equipment capacities

Open Pit Mining Production Scheduling

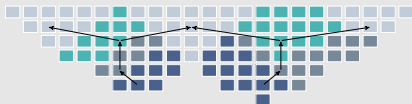
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- ▷ possibly aggregation of blocks

Open Pit Mining Production Scheduling

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Problem

Find an excavation schedule with

- ▷ max. net present value

satisfying

- ▷ precedence constraints,
- ▷ resource constraints.

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Getting started: computing ultimate pit limits

Given: Profit/negative cost w_i of mining each block $i \in \mathcal{N} = \{1, \dots, N\}$.

Seek: Precedence-feasible set of blocks $X \subseteq \mathcal{N}$ with $\max. \sum_{i \in X} w_i$.
(If $i \in X$ than all predecessors of i are in X .)

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Observation: This is a **max-weight closure problem** in the precedence graph

$$(\mathcal{N}, \mathcal{S} = \{(i, p) \in \mathcal{N} \times \mathcal{N} \mid p \text{ predecessor of } i\})$$

with node weights w_i .

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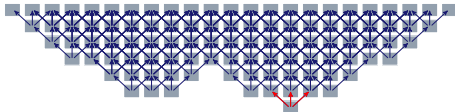
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- ▷ Solve e.g. by min-cut algorithm in a slightly extended graph:



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A simple time-indexed IP formulation

max *NetPresentValue* (x)

s.t.

$x_{i,t-1} \leq x_{i,t}$	for $i \in \mathcal{N}, t = 1, \dots, T - 1$
$x_{i,t} \leq x_{k,t}$	for $i \in \mathcal{N}, k \in \mathcal{P}(i), t = 0, \dots, T - 1$
$\sum_i R_i x_{i,t} \leq (t + 1)M$	for $t = 0, \dots, T - 1$
$\sum_i O_i x_{i,t} \leq (t + 1)P$	for $t = 0, \dots, T - 1$
$x_{i,t} \in \{0, 1\}$	for $i \in \mathcal{N}, t = 0, \dots, T - 1$
$x_{i,-1} = 0$	for $i \in \mathcal{N}$

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Precedence Constrained Knapsack Problem

Given:

- ▷ Items $i \in \mathcal{N}$ with sizes a_i and values c_i
- ▷ Knapsack capacity b
- ▷ Precedence order $\mathcal{S} \subseteq \mathcal{N} \times \mathcal{N}$ (transitively reduced)

Feasible Solution:

- ▷ set $X \subseteq \mathcal{N}$ with $\sum_{i \in X} a_i \leq b$ and
- ▷ X is closed under \mathcal{S} (If $i \in X$ and $(i, j) \in \mathcal{S}$, then $j \in X$.)

Goal: maximize $\sum_{i \in X} c_i$

Important substructure in many applications:

- ▷ Resource constrained scheduling
- ▷ Multi-level facility location, access & distribution network design
- ▷ Routing problems: confluent flows, Internet routing, ...
- ▷ ...

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PCKs in open pit mining

$$\max \quad \text{NetPresentValue}(x)$$

$$\begin{aligned} \text{s.t.} \quad & x_{i,t-1} \leq x_{i,t} && \text{for } i \in \mathcal{N}, t = 1, \dots, T-1 \\ & x_{i,t} \leq x_{k,t} && \text{for } i \in \mathcal{N}, k \in \mathcal{P}(i), t = 0, \dots, T-1 \\ & \sum_i R_i x_{i,t} \leq (t+1)M && \text{for } t = 0, \dots, T-1 \\ & \sum_i O_i x_{i,t} \leq (t+1)P && \text{for } t = 0, \dots, T-1 \\ & x_{i,t} \in \{0, 1\} && \text{for } i \in \mathcal{N}, t = 0, \dots, T-1 \\ & x_{i,-1} = 0 && \text{for } i \in \mathcal{N} \end{aligned}$$

$$x_{i,t} \leq x_{k,t} \quad \text{for } i \in \mathcal{N}, k \in \mathcal{P}(i)$$
$$\sum_i R_i \leq (t+1)M$$

$$x_{i,t} \in \{0, 1\} \quad \text{for } i \in \mathcal{N}$$

- ▷ For each time period t , the OPMPSP formulation contains two precedence constrained knapsacks (for mining and processing constraints).

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Precedence Constrained Knapsack Polytope

$$PCKP := \text{conv} \left\{ x \in \{0, 1\}^{\mathcal{N}} \mid \sum_{i \in \mathcal{N}} a_i x_i \leq b, \right. \quad (i)$$
$$\left. x_i \leq x_j \text{ for } (i, j) \in \mathcal{S} \right\} \quad (ii)$$

Polyhedral structure of *PCKP* well studied:

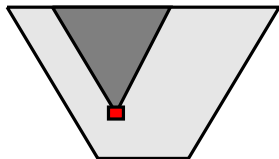
- ▷ Dimension, Conditions for (i) and (ii) to be facet-defining
- ▷ Knapsack-based inequalities [Boyd'93, Park-Park'97]
 - ▷ Induced cover inequalities
 - ▷ (Induced) k-cover inequalities
 - ▷ (Induced) (1,k)-configuration inequalities
- ▷ Sequential lifting results [v.d.Leensel-v.Hoesel-v.d.Klundert'99]

But:

- ▷ Nothing implemented in MIP solvers

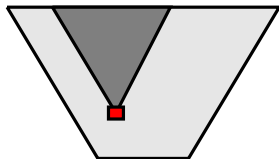
Notation

- ▷ $Pred(i) := \{j : j \text{ predecessor of } i\} \cup \{i\}$
(Items that must be included with i .)
- ▷ $A(i) := \sum_{j \in Pred(i)} a_j$
(Total size induced by i .)



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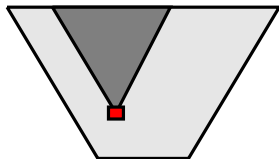
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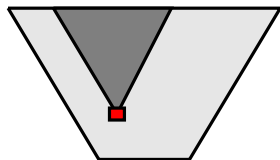
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Variable elimination scheme

- ▷ If $A(i) > b$, fix $x_i = 0$.

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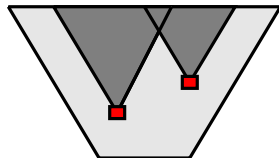
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Remarks

- ▷ Can compute *all* $A(i)$ in $\mathcal{O}(\mathcal{S})$.
- ▷ Fixing is very efficient in practice (reduces LP gaps substantially).
- ▷ **CPLEX does not find these fixings** (even with aggressive probing).

Apply same idea to pairs of items:

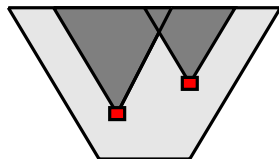
- ▷ $A(i, j) := \sum_{k \in \text{Pred}(i) \cup \text{Pred}(j)} a_k$
(Total size of i , j and predecessors.)



Apply same idea to pairs of items:

$$\triangleright A(i, j) := \sum_{k \in \text{Pred}(i) \cup \text{Pred}(j)} a_k$$

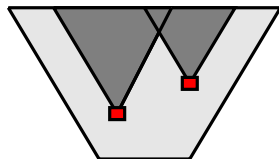
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Observation: If $A(i, j) > b$, then $x_i + x_j \leq 1$ for all $x \in PCKP$.

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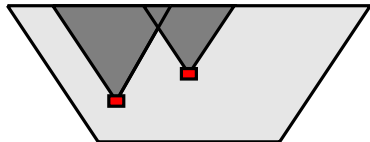
- ▷ $\{i, j\}$ with $A(i, j) > b$: Induced cover of size 2
- ▷ Induced cover: $X \subset \mathcal{N}$ with $A(X) > b$
- ▷ [Boyd'93, Park-Park'97] Conditions when induced cover inequalities are facet-defining (for low-dimensional faces of PCKP)
- ▷ [v.d.Leensel-v.Hoesel-v.d.Klundert'99] Lifting facet-defining inequalities for low-dimensional faces of PCKP to facets of PCKP

Clique inequalities

Idea

- ▷ Consider clique graph $CG = (\mathcal{N}, E)$ with $E := \{ij \mid A(i, j) > b\}$

Precedence order



Clique graph CG

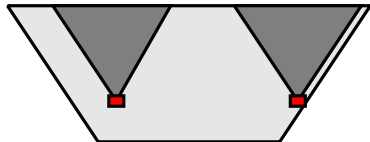


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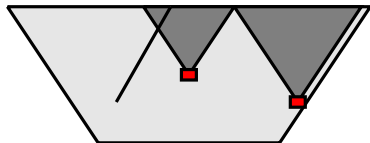


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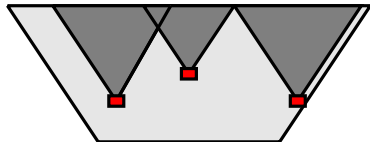


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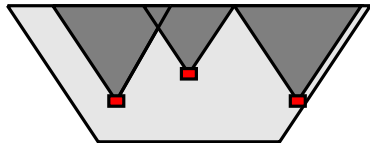


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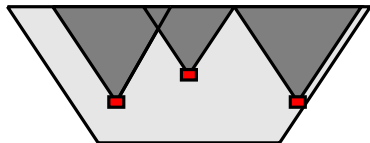
Observation: Any valid inequality for $STAB(CG)$ is valid for $PCKP$.

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Clique graph CG



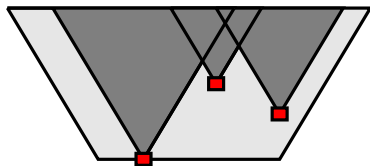
Observation: Any valid inequality for $STAB(CG)$ is valid for $PCKP$.

Corollary: Let C be a clique in CG . Then (1) is valid for $PCKP$.

$$\sum_{i \in C} x_i \leq 1 \quad (1)$$

Cliques with common predecessors

Precedence order



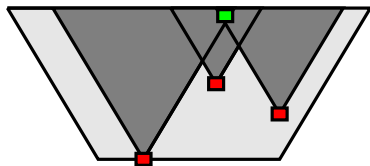
Extended clique graph

CG'



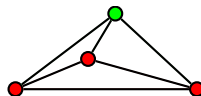
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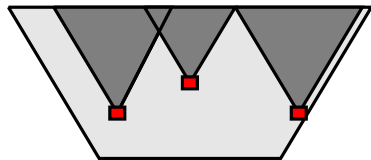
Observation: Let C be a clique in CG with $P(C) = \bigcap_{i \in C} \text{Pred}(i) \neq \emptyset$. Then, for any $i \in P(C)$,

$$\sum_{j \in C} x_j \leq x_i \quad (2)$$

is valid for $PCKP$.

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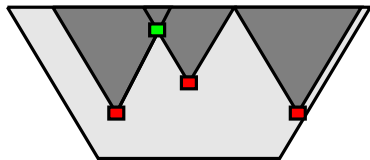
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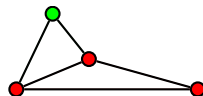
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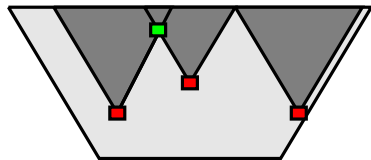
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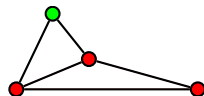
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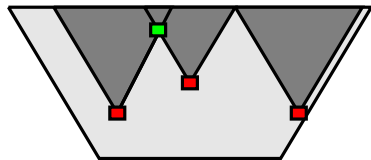
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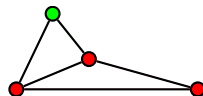
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$$\sum_{j \in C} x_j + \bar{x}_i \leq 1 \quad (2)$$

is valid for $PCKP$.

Separation of clique-based inequalities

Given: $x \in [0, 1]^N$ fractional

Seek:

- (1) clique C in CG such that $\sum_{j \in C} x_j > 1$, or
- (2) clique C in CG and $i \in P(C)$ such that $\sum_{j \in C} x_j > x_i$

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▷ Separation of (1) and (2) is equivalent to finding a *maximum-weight clique* in CG' with node weights $w_k := x_k$ and $w_{k'} := 1 - x_k$ for all $k \in \mathcal{N}$

▷ $w(C^*) \leq 1$: all inequalities (1) and (2) satisfied

▷ $w(C^*) > 1$ and $C^* \subseteq \mathcal{N}$: inequality (1) violated

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 - ▷ $w(C^*) \leq 1$: all inequalities (1) and (2) satisfied
 - ▷ $w(C^*) > 1$ and $C^* \subseteq \mathcal{N}$: inequality (1) violated
 - ▷ $w(C^*) > 1$ and $C^* = C \cup \{\bar{i}\}$: inequality (2) violated
- ▷ NP-hard, but: Efficient MWC implementations exist in any state-of-the-art MIP solver.
- ▷ Ideally: extend the clique graph of your MIP solver.

More details on facets and computational results: see e.g.

Boland-Froyland-Fricke-Sotirov'06, Bley-Boland-Fricke-Froyland'09.

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