

## Node-Arc Incidence-Matrices

Let us start with an example of network matrices:

### Theorem 14.22 (Poincaré, 1900).

Let  $A$  be a matrix with entries in  $\{-1, 0, 1\}$ , where each column has at most one  $+1$  and at most one  $-1$ . Then  $A$  is TUM.

Proof: ... □

### Corollary 14.23.

Let  $D = (V, E)$  be a directed graph and let  $A$  be the node-arc incidence matrix of  $D$  with entries

$$a_{ve} := \begin{cases} +1 & \text{if } v \text{ is the head of } e, \\ -1 & \text{if } v \text{ is the tail of } e, \\ 0 & \text{otherwise.} \end{cases}$$

Then  $A$  is TUM.

Example: ...

427

## Network Matrices

### Definition 14.24.

Let  $D = (V, E)$  be a digraph and  $T = (V, E')$  be a spanning tree of  $D$ . Then  $M \in \{-1, 0, 1\}^{E' \times E}$  with entries

$$M_{e',(u,v)} := \begin{cases} +1 & \text{if the } (u, v)\text{-path in } T \text{ uses } e' \text{ in forward direction,} \\ -1 & \text{if the } (u, v)\text{-path in } T \text{ uses } e' \text{ in backward direction,} \\ 0 & \text{otherwise.} \end{cases}$$

is called **network matrix** (w.r.t.  $D$  and  $T$ ).

Example: ...

### Theorem 14.25 (Tutte, 1965).

Network Matrices are TUM.

Proof: ... □

428

## Examples of Network Matrices

### Observation 14.26.

Node-arc incidence matrices are network matrices.

Proof: ...

□

### Observation 14.27.

Let  $G = (V, E)$  be a bipartite graph and  $M \in \{0, 1\}^{V \times E}$  its node-edge incidence matrix with entries  $M_{v,e} = 1$  iff  $v$  is incident to  $e$ . Then  $M$  is a network matrix.

Proof: ...

□

### Observation 14.28.

A  $\{0, 1\}$ -matrix  $A$  is said to have the **consecutive-ones-property** if the 1's in each column occur consecutively. Such a matrix is a network matrix.

Proof: Exercise.

□

429

## Total Dual Integrality

Min-max results on combinatorial objects can often be achieved by applying the *LP*-duality

$$\max\{w^T x \mid Ax \leq b\} = \min\{y^T b \mid y^T A = w^T, y \geq 0\}. \quad (14.1)$$

### Definition 14.29.

A rational linear system  $Ax \leq b$  is **totally dual integral (TDI)** if the minimum in (14.1) can be achieved by an integral vector  $y$  for each integral  $w$  for which optima exist.

### Theorem 14.30 (Hoffman'74).

Let  $Ax \leq b$  be a TDI-system with integral  $b$  such that  $P = \{x \mid Ax \leq b\}$  is a rational polytope. Then  $P$  is integral.

Proof: ...

□

430

## TDI-Systems always exist!

### Theorem 14.31 (Giles/Pulleyblank'79).

Let  $P$  be a rational polyhedron. Then there exists a TDI-system  $Ax \leq b$  with integral  $A$  such that  $P = \{x \mid Ax \leq b\}$ . Furthermore, if  $P$  is integral, then  $b$  can be chosen to be integral.

**Proof:** omitted. (Rough idea: Given  $P = \{x \mid \tilde{A}x \leq \tilde{b}\}$ , add a (redundant) inequality for each integral point that can be written as a nonnegative combination of the rows in  $\tilde{A}$ .) □

Possible approach to prove the integrality of polyhedra:

- 1 Find an appropriate defining system  $Ax \leq b$  with  $A$  and  $b$  integral.
- 2 Prove that  $Ax \leq b$  is TDI.
- 3 Conclude with Theorem 14.30 that  $\{x \mid Ax \leq b\}$  is integral.

The usefulness of this plan strongly depends on methods for proving TDI-ness of systems.

→ Important research branch!

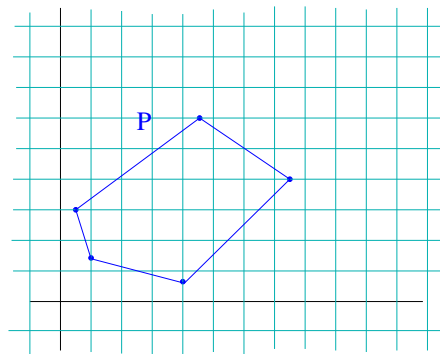
431

## Cutting Planes

Given an ILP of the form

$$(ILP) \quad \max\{w^T x \mid Ax \leq b, x \text{ integer}\},$$

where  $P = \{x \mid Ax \leq b\}$  is *not integral*, we may still use linear-programming technique to find good solutions for this *special*  $w$ .



**Observe:**  $x_2 \leq 5$  for all integral points in  $P$ .

**Idea:** Given an integral solution  $\bar{x}$  of  $Ax \leq b$  with  $w^T \bar{x} = t$ , in order to show the optimality of  $\bar{x}$  we need to show that  $w^T x \leq t$  holds for all integral vectors in  $P = \{x \mid Ax \leq b\}$ . **Example:** ...

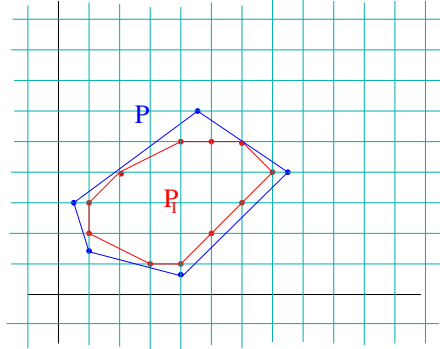
432

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432

## Gomory-Chvátal Cutting Planes

### Definition 14.32.

A **cutting plane** (or **cut**) of a polyhedron  $P$  is an inequality that is valid for all integral vectors in  $P$ .

### Observation 14.33.

Let  $P = \{x \mid a_i^T x \leq b_i (i = 1, \dots, m)\}$  and  $y \in \mathbb{R}_+^m$ . Then, for  $c = \sum_{i=1}^m y_i a_i$  and  $d = \sum_{i=1}^m y_i b_i$ , the inequality  $c^T x \leq \lfloor d \rfloor$  is a cutting plane.

If  $c$  is integral, then  $c^T x \leq \lfloor d \rfloor$  is called **Gomory-Chvátal cutting plane** of  $P$ .

Gomory and Chvátal pioneered such a cutting plane approach to integer programming.

433